

Recovery from "Check Position" Message

Introduction

This document describes how to recover from a "Check Position" message on the bottom of the pendant, as shown below.

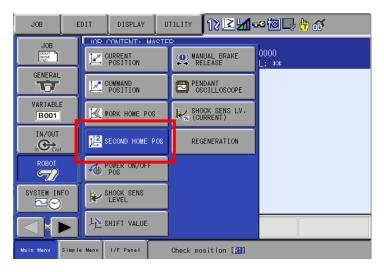
JOB	EDIT	DISPLAY	UTILITY	1224~0	3 🖵 🙌 🚮
	J:Jo	CONTENT: MA b ROL GROUP:		S:0000 TOOL: >	
GENERAL		NOP 1 END			
VARIABLE					
ROBOT					
SYSTEM IN	F0				
Main Menu	Simple Menu	I/F Panel	Check p	osition [<mark>R1</mark>]	



Recovery Procedure

NOTE: This procedure can be completed in any security level with no outstanding alarms.

1. Select ROBOT and then SECOND HOME POS.



JOB	SECOND HOME I	POS	-		
DOUT		PECIFIED	CURRENT	DIFFERENCE	
	R1 :S	0	318514	318514	
GENERAL	L	0	-134649	134649	
कि	U	0	-41785	41785	
	R	0	-671163	671163	
VARIABLE	В	0	-184955	184955	
B001	Т	0	-114443	114443	
IN/OUT					
ROBOT					
$\langle \neg \rangle$					
SYSTEM INFO					
	1 <u> </u>	1		1	
Main Menu Simple	: Menu I/F Panel	Check p	osition [<mark>R1</mark>]		

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- Default SPECIFIED position "0" in column. The orientation of robot/station will vary based upon model.
- SPECIFIED position can be modified if needed to accommodate for cell layout

JOB		SECO	ND HOME P	'OS					
DOUT MOVE				ECIFIED	CU	IRRENT	DIFFE	RENCE	
END		R1 :	S	0		18514		18514	
GENERAL			L	0		34649		34649	
	1		U	0		41785		41785	
	-		R	0	-	71163	-	71163	
VARIABL			В	0		84955		34955	
B001			T	0	-1	14443	1	14443	
IN/OUT					-				
	it 👘								
ROBOT									
97									
	-								
SYSTEM IN	NFO								
[] H									
Main Menu	Simple	Menu	I/F Panel	Check	position	[<u>R1</u>]			

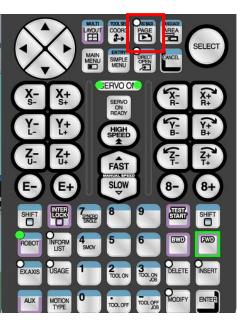
- 2. If this is a single robot without an external axis, skip to step 5. Controllers with multiple groups(robot(s) and/or station(s)), continue to step 3.
- 3. Confirm origin of Check position, highlighted in message.





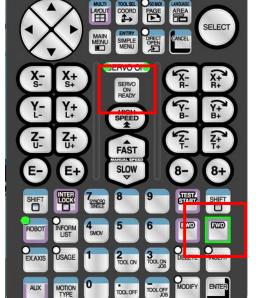
- 4. Use the PAGE icon on the lower screen or the teach pendant PAGE key to select the group highlighted in the message.
 - Selected group shows in top left corner

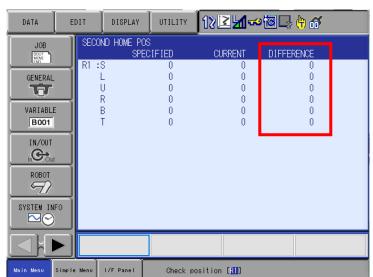
DATA	EDIT	DESPLAY	UTILETY	12 🗷 🖌	ا 🛃 📑 😣	þ 🕨
SECOND HO			-			
	SPECIFIED	0	URRENT	DIFFERENCE		
RI :S	Q		Q	0		
L.	0		0	0		
U	U		0	U		
R B	0		0	U		
Б	0		0 0	0		
1	v		v	0		
				RT: ROBOTT		
				S1:STATION1 S2:STATION2		
_				02.0TATION2		
				PHOL		





- 5. Engage servos and hold the FWD key until robot DIFFERENCE column reads all "0"
 - Robot will move to SPECIFIED position.
 - Use caution when moving the robot. Be aware of possible interference.
 - Manual JOINT jogging may be required to avoid interferences to complete motion to the SPECIFIED position
 - Cartesian motion (Robot, User, and Tool) may not work with Check position message







PARTNER SUPPORT
Shared Integration Experience

This document captures ideas, experiences, and informal recommendations from the Yaskawa Partner Support team. It is meant to augment – not supersede manuals or documentation from motoman.com. Please contact the Partner Support team at partnersupport@motoman.com for updates or clarification.

6. Press DATA in top left of display screen and CONFIRM POSITION

DATA	EDIT	DISPLAY	UTILITY	1224~	v 🙋 📮 🕆 🎸	
CONFIRM POSITION			DIFIED	CURRENT	DIFFERENCE	
GENERAL	R1 :	S L II	0 0 0	0 0	0 0 0	
VARIABLE		R B	0 0	0 0	0 0	
IN/OUT		Т	0	0	0	
ROBOT						
SYSTEM INF	0					
Main Menu S	Main Menu Simple Menu 1/F Panel Check position [1]					



7. The Check position message will change to Home Position checked. If the Check Position message remains, multiple groups may need confirmed. Repeat steps with remaining group(s) requiring position check.

DATA	DIT	DISPLAY	UTILITY	12≧⊿∽	ه () چاھ	
JOB DOUT MOVE			S SIFIED	CURRENT	DIFFERENCE	
GENERAL	R1 :S L	} - J	0 0 0	0 0 0	0 0 0	
VARIABLE	F		0 0	0 0	0 0	
IN/OUT			Ų	Ų	U	
SYSTEM INFO						
	L	_				
Main Menu Simpl	e Menu	I/F Panel	Home pos	sition checked		